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ROBUST F0 ESTIMATION BASED ON A MULTICHANNEL PERIODICITY FUNCTION FOR DISTANT-TALKING SPEECH

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Outline

❑ Acoustic scene analysis for ambient intelligence

- Principal dimensions of distant-talking analysis and ASR
- Limitations of the common approach
- Distributed Microphone Network
- CHIL room for seminars and meetings (CHIL European Project)
- CurrentIRST activities

❑ Robust F0 estimation

- Single channel algorithms: WAUTOC, YIN
- Multichannel algorithms: WAUTOC, YIN
- Multichannel Periodicity Function (MPF)

❑ Preliminary results

- Multichannel corpus derived by the Keele database

❑ Conclusions and future perspectives

Principal dimensions of distant-talking analysis and ASR

- ❑ Type and location of microphones
- ❑ Talker position, direction, and head rotation
- ❑ Talker speech clarity, SNR
- ❑ Possible talker position changes
- ❑ Environmental noise and acoustics
 - Echoes and reverberation
 - Noise level, noise source positions
 - Diffuse or coherent noise (stationary vs unstationary)
 - From babble noise to competitive talkers

Limitations of the common approach

- ❑ Need of a rather controlled acoustic environment
 - Limit reverberation and noise
- ❑ Assumption to have one speaker (vs competitive speakers)
- ❑ Head orientation and speech clarity dependency
- ❑ Room coverage limitations
 - Microphone arrays placement constrained by room geometry
 - Placed sensors may result intrusive
 - Need of expensive microphones/technology

Distributed Microphone Network

❑ Ubiquitous sensing

- Wall-mounted T-shaped (low-cost) microphone clusters
- Microphone arrays
- Table microphones, etc

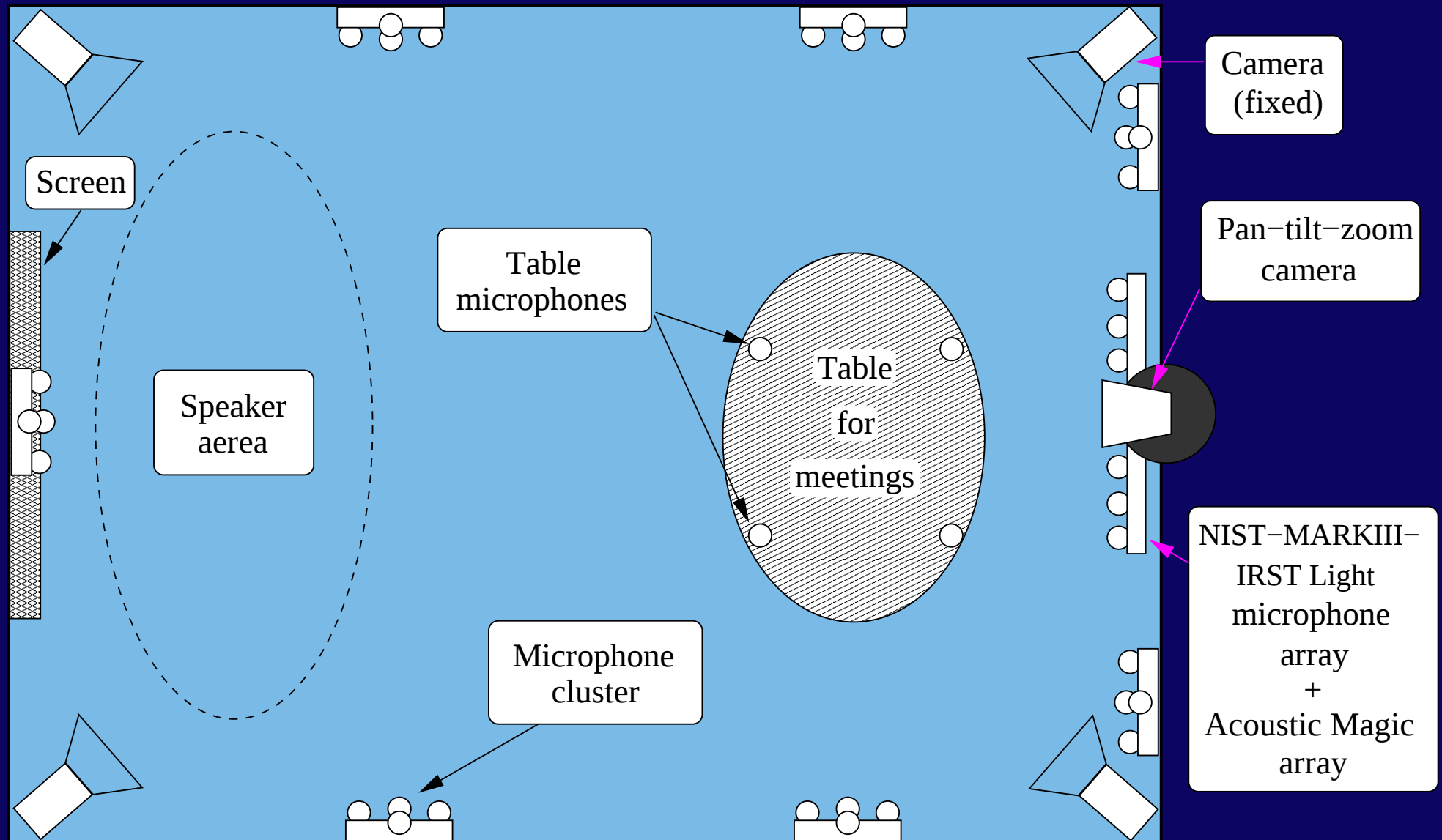
❑ Main objective

- Analysis and interpretation of the scenario
- Integration with visual information provided by cameras

❑ Possible applicative contexts:

- Security and surveillance
- Videoconferencing
- Smart home (television control, elderly and disabled assistance, etc)
- Meeting rooms, lecture rooms (CHIL project)

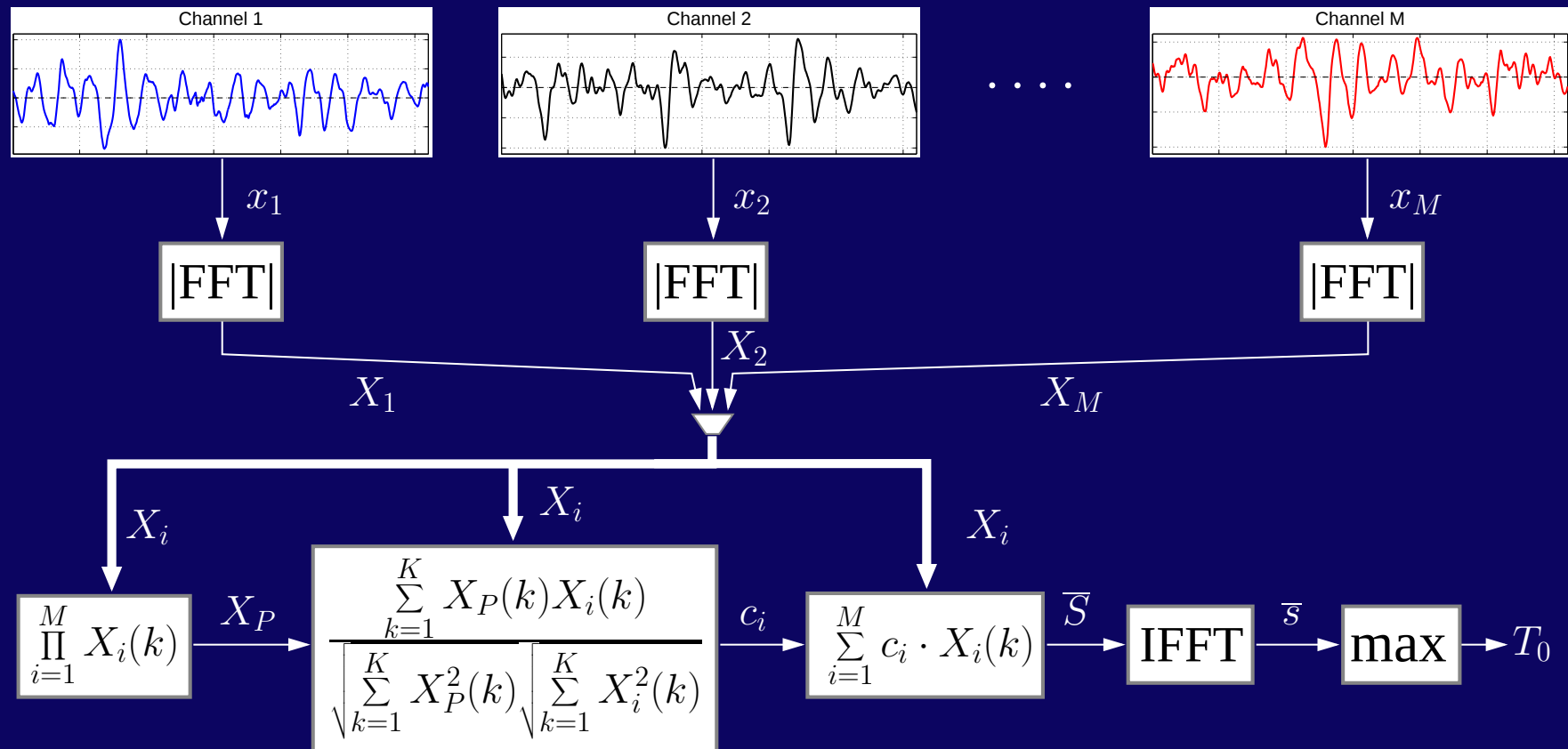
CHIL room for seminars and meetings



Current IRST activities

- ❑ Speech activity detection
- ❑ Acoustic Event Detection (AED)
- ❑ Speaker(s) localization (tracking position and orientation)
- ❑ Distant-talking ASR
- ❑ Audio-video integration, person identification, etc
- ❑ Multi-microphone pitch analysis

MPF - Multichannel Periodicity Function



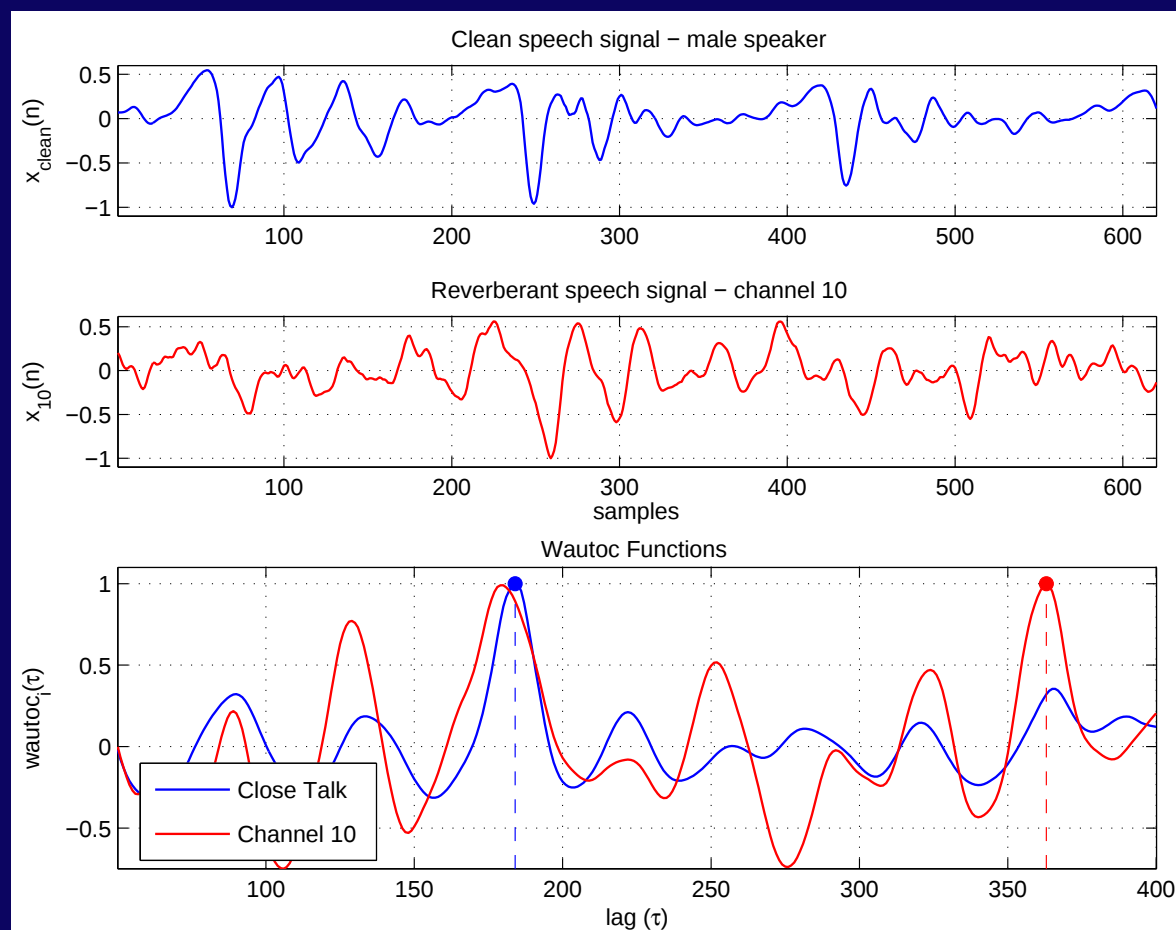
- x_i = i -th channel signal
- X_i = i -th channel $|FFT|$
- X_P = reference spectrum
- c_i = i -th channel weight
- $\bar{s}$ = MPF
- T_0 = estimated period

Weighted Autocorrelation (single channel)

$$wautoc_i(\tau) = \frac{\sum_{n=0}^{N-\tau-1} x_i(n)x_i(n+\tau)}{\sum_{n=0}^{N-\tau-1} |x_i(n) - x_i(n+\tau)| + \epsilon}$$

T. Shimamura

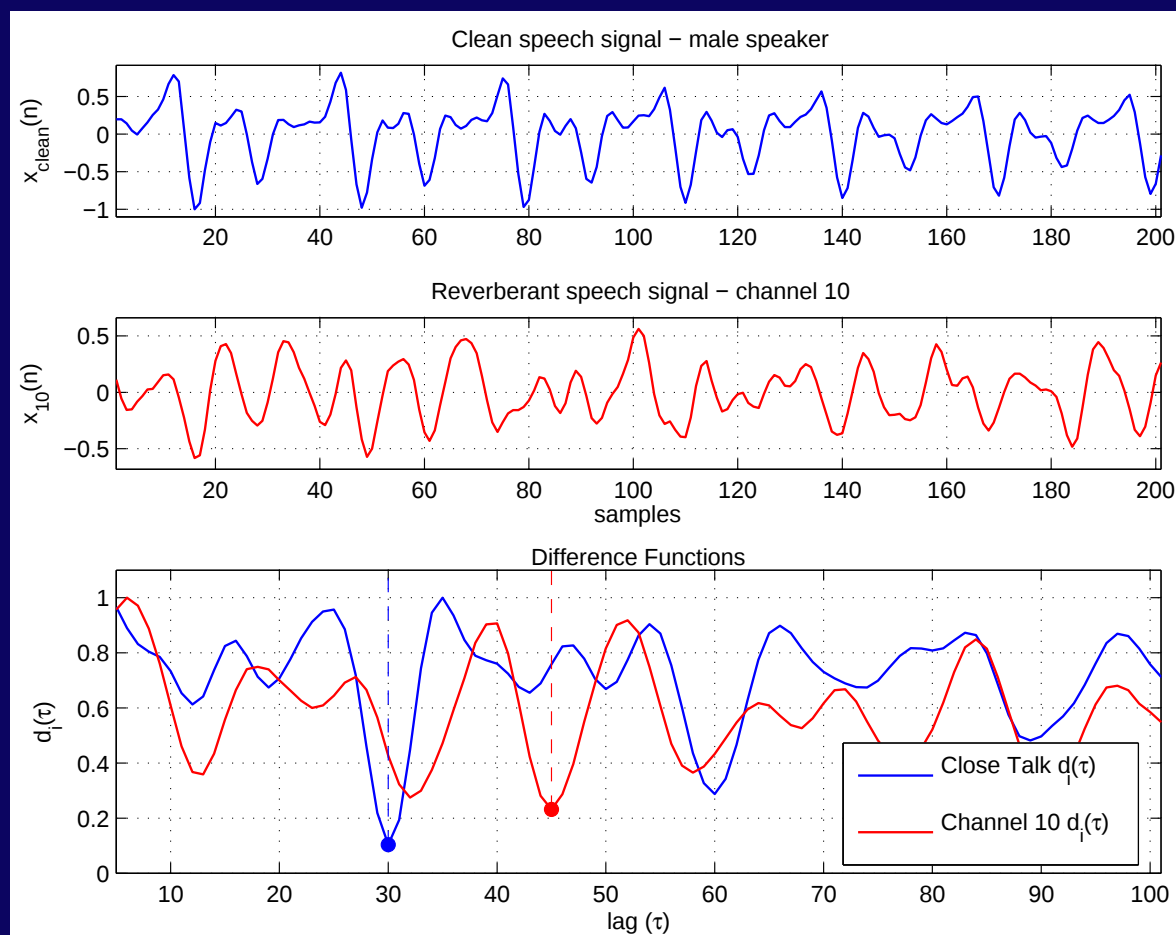
H. Kobayashi



YIN - Cumulative Mean Normalized Difference function (single channel)

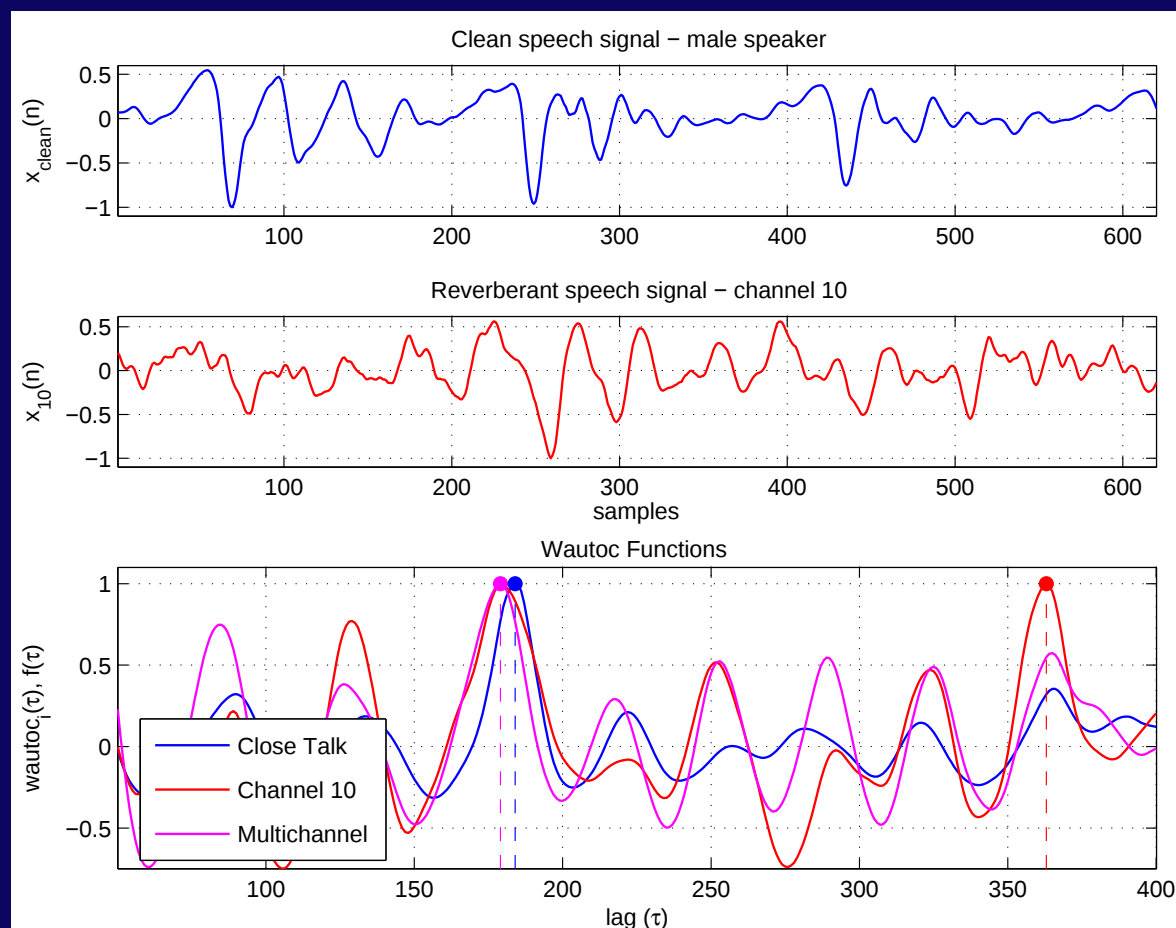
$$d_i(\tau) = \sum_n [x_i(n) - x_i(n + \tau)]^2, \quad d'_i(\tau) = \begin{cases} 1, & \text{if } \tau = 0, \\ d_i(\tau) / [(1/\tau) \sum_{j=1}^{\tau} d_i(j)] \end{cases}$$

A. de Cheveigné
H. Kawahara



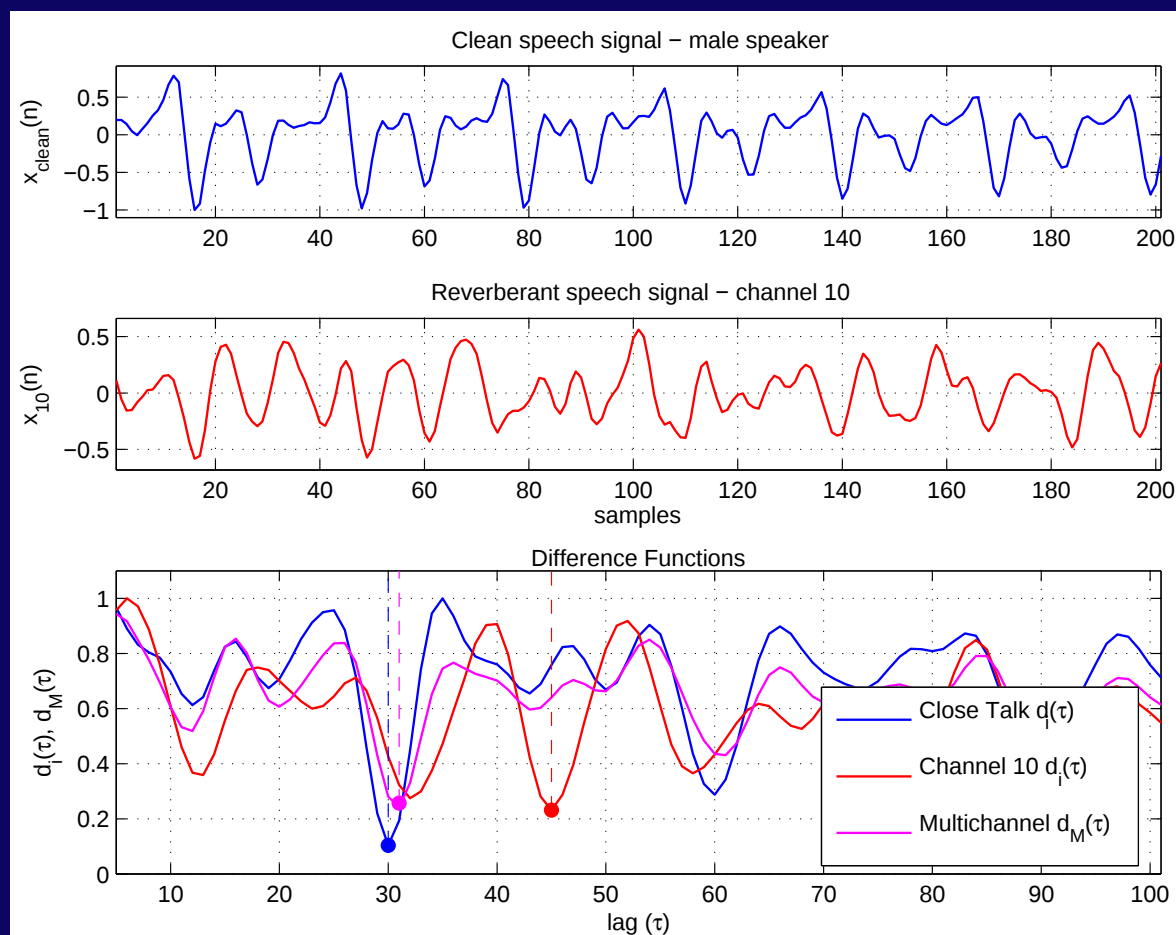
Weighted Autocorrelation (multichannel extension)

$$wautoc_i(\tau) = \frac{\sum_{n=0}^{N-\tau-1} x_i(n)x_i(n+\tau)}{\sum_{n=0}^{N-\tau-1} |x_i(n) - x_i(n+\tau)| + \epsilon} \quad \blacktriangleright \blacktriangleright \blacktriangleright \quad f(\tau) = \sum_{i=1}^M wautoc_i(\tau)$$



YIN (multichannel extension)

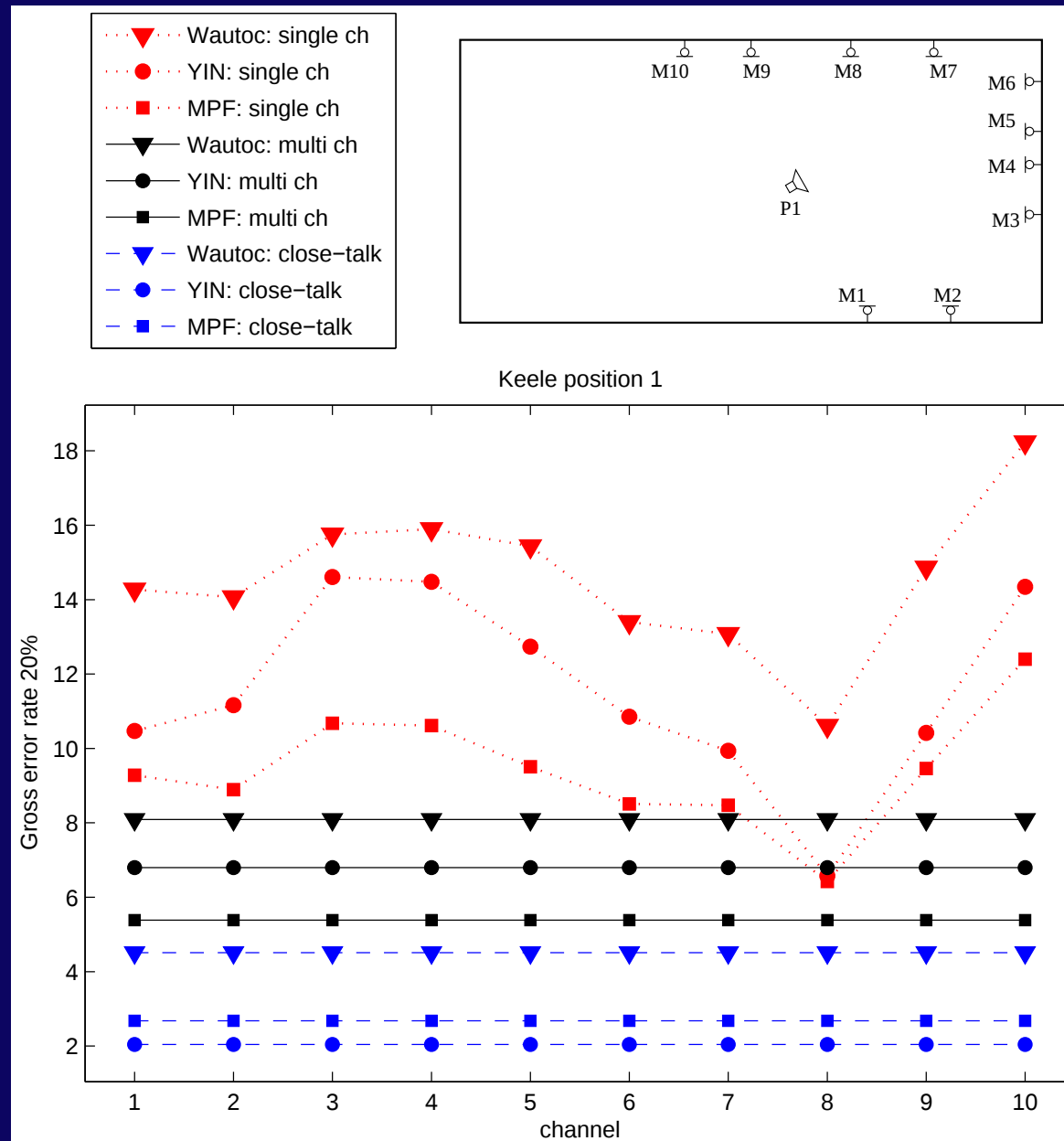
$$d_M(\tau) = \frac{1}{M} \sum_{i=1}^M d_i(\tau) \quad \blacktriangleright \blacktriangleright \blacktriangleright \quad d_i''(\tau) = \begin{cases} 1, & \text{if } \tau = 0, \\ d_M(\tau) / [(1/\tau) \sum_{j=1}^{\tau} d_M(j)] \end{cases}$$



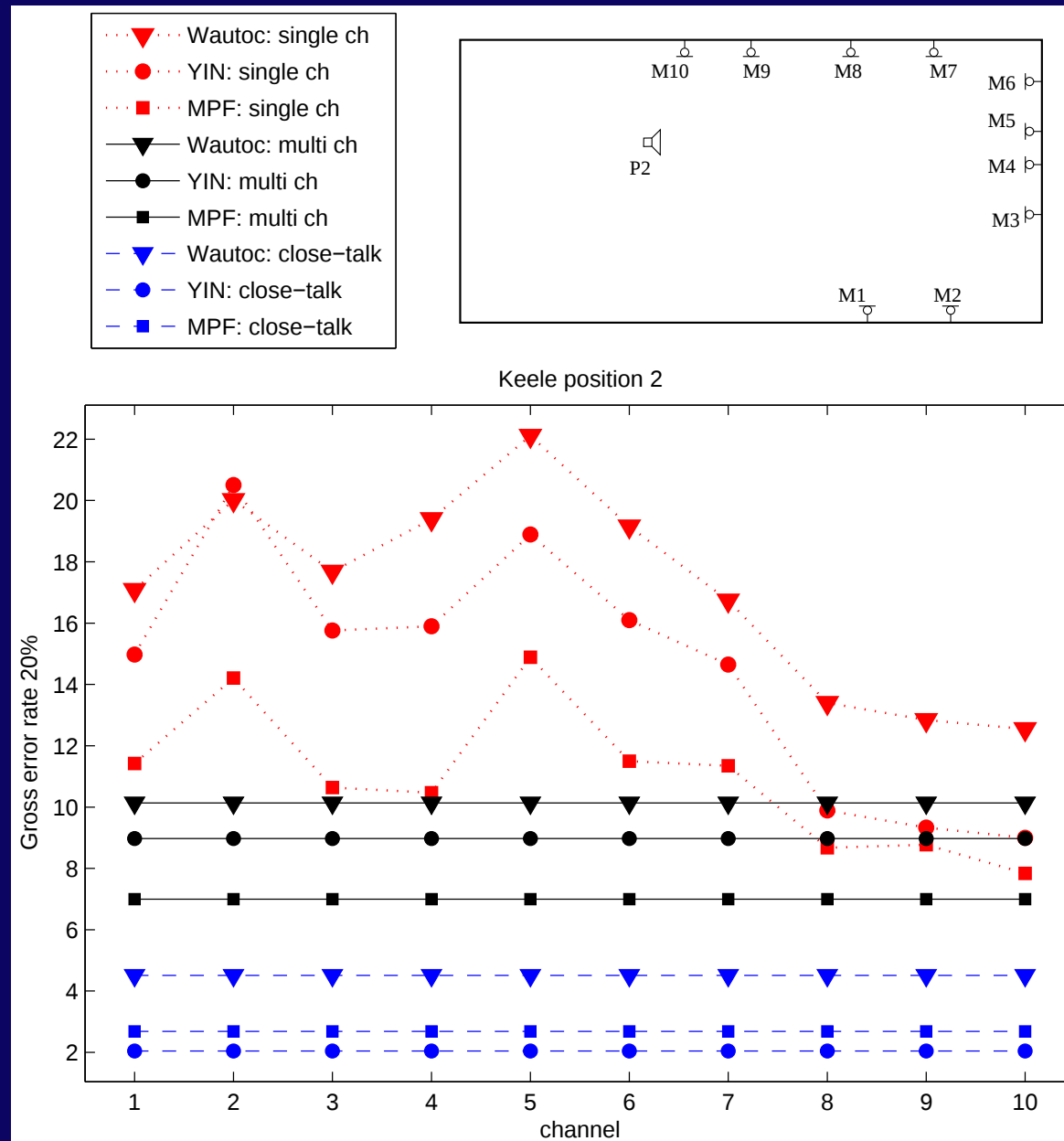
- Keele Database reproduced in position P1 and P2
- Recorded by 10 omnidirectional microphones
- Pitch references extracted from laringograph signal
- Reverberation time $T_{60} \simeq 0.35s$



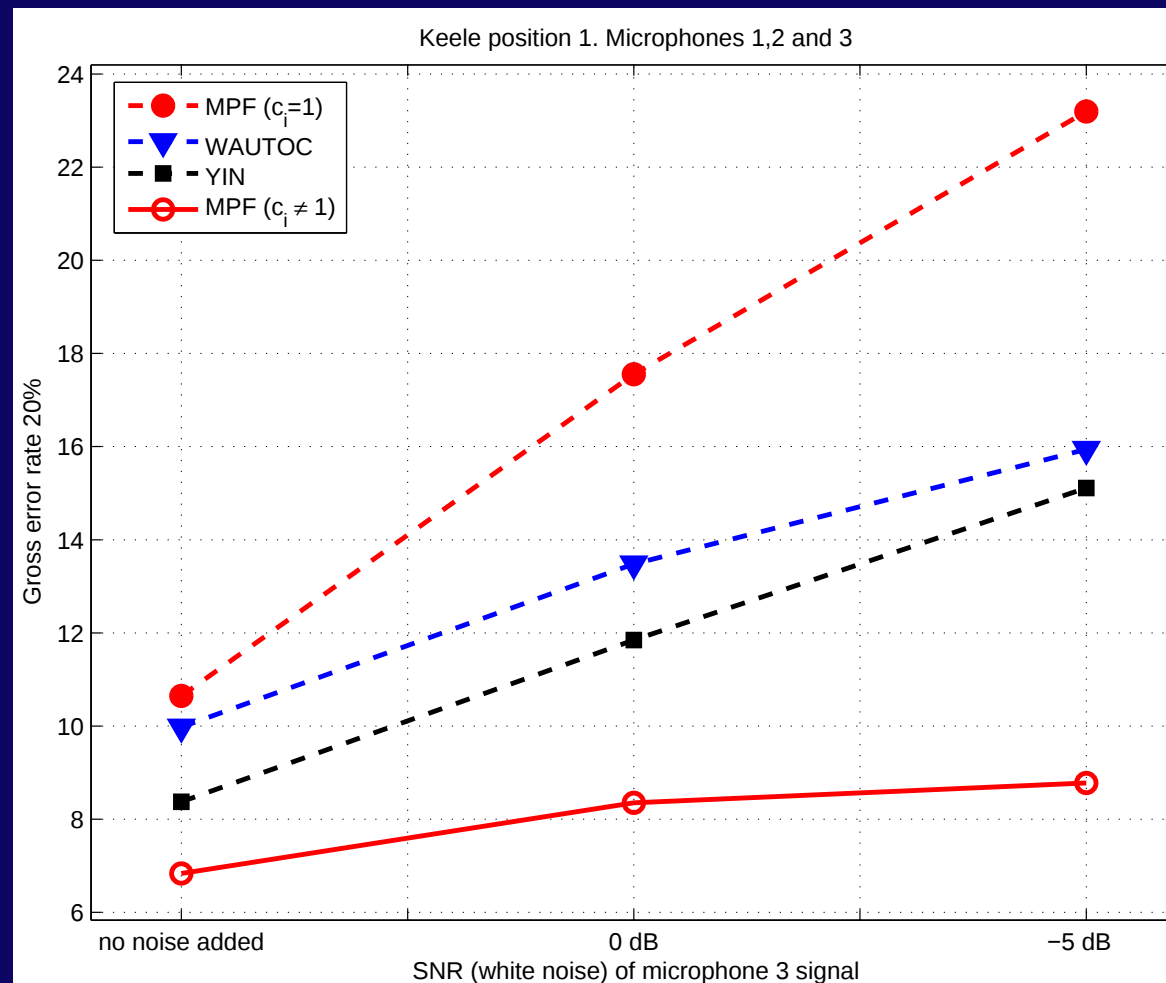
Wautoc, YIN, MPF (Gross Error Rate 20% - position P1)



Wautoc, YIN, MPF (Gross Error Rate 20% - position P2)



MPF channel reliability estimation (mics 1,2 and 3 - position P1)



- White noise added to channel 3 at different SNR
- MPF algorithm selects best channels (1 and 2) for F0 estimation

Conclusions

- Phase distortion introduced by reverberation is best handled by a frequency-domain approach (MPF)
- FFT based algorithms can easily perform real-time processing
- Channel reliability estimation permits to process concurrent activities independently

Future perspectives

- Test MPF performance on meeting and seminar data recorded in the IRST CHIL room
- Integration of F0 information to distant talking ASR (LPC pitch synchronous analysis)

Thank you very much